

Immersive Web-based Classification Correction of Point Cloud Data

Thomas J. Pingel^{a*} and Hudson Chase^a

^a Department of Geography, Virginia Polytechnic Institute and State University, Blacksburg, VA, USA

* tpingel@vt.edu

Keywords: point cloud, virtual reality, classification, lidar, interactive machine learning

Despite many advances in algorithm development for the classification of point cloud data from lidar, photogrammetric, and other sources, such systems are only roughly 90% efficient (Pingel et. al, 2012; Jeong and Lee, 2016; Becker et al., 2017). While improvements to algorithms can, should, and undoubtedly will continue (Grilli et al., 2017), there remains a rationale in some cases for a human-in-the-loop (HITL; Holzinger, 2016). HITL-based systems may directly improve the classification itself or, more usefully, for improved products derived from the point cloud (e.g., ground classification of a lidar point cloud to yield a more accurate digital terrain model). More significantly, more accurately classified point clouds may spur the development of better classification algorithms by acting as improved training and “ground truth” data in a feedback loop referred to as Interactive Machine Learning (Ware et al., 2001; Amershi et al., 2014).

Recent advancements in virtual reality platforms make an immersive, open-source system for classification correction much more feasible. First, hardware platforms such as the Oculus Rift and Quest, the HTC Vive, and Microsoft HoloLens are now commercially viable and in mass production with well-used APIs and strong development support. Second, web delivery and manipulation of point clouds and other kinds of large spatial datasets are now well-supported via Potree (Schuetz, 2016), CesiumJS (Cozzi, 2012), Plasio (Verma and Butler, 2014), and Entwine (Manning, 2019). And third, web-based virtual reality content has greatly matured through JavaScript libraries and specifications such as WebVR, three.js, and A-Frame. The nexus of these and other related technologies has significantly lowered the barriers toward the development of an immersive, web-based, and open-source point cloud interaction system.

Research in this domain has already shown the potential of immersive point cloud visualization systems for interaction with these complex data sets (Kreylos et al., 2008; Burwell et al., 2012). We present our work-in-progress for the development of such a system based on web-delivery of immersive point cloud content with the intent of engaging with the GIS and Geovisualization community to further drive development. We detail efforts to solve technical problems of integration as well as user interface issues associated with navigation and interaction, and detail future work implementing multiple feedback loops between algorithmic classification and user correction.

References

- Amershi, S., Cakmak, M., Knox, W. B., & Kulesza, T. (2014). Power to the people: The role of humans in interactive machine learning. *AI Magazine*, 35(4), 105-120. doi: 10.1609/aimag.v35i4.2513
- Becker, C., Häni, N., Rosinskaya, E., d'Angelo, E., & Strecha, C. (2017). Classification of aerial photogrammetric 3D point clouds. *The International Archives of Photogrammetry, Remote Sensing and Spatial Information Sciences*, IV-1/W1, 3-10. doi:10.5194/isprs-annals-IV-1-W1-3-2017
- Burwell, C., Jarvis, C., & Tansey, K. (2012). The potential for using 3D visualization for data exploration, error correction and analysis of LiDAR point clouds. *Remote sensing letters*, 3(6), 481-490. doi:10.1080/01431161.2011.629233
- Cozzi, P. (2013, September). *Cesium: 3D maps for the web*. Paper presented at FOSS4G, Nottingham, UK.
- Holzinger, A. (2016). Interactive machine learning for health informatics: when do we need the human-in-the-loop? *Brain Informatics*, 3(2), 119-131. doi: 10.1007/s40708-016-0042-6
- Grilli, E., Menna, F., & Remondino, F. (2017). A review of point cloud segmentation and classification algorithms. *The International Archives of Photogrammetry, Remote Sensing and Spatial Information Sciences*, XLII-2/W3, 339-344. doi: 10.5194/isprs-archives-XLII-2-W3-339-2017
- Jeong, J., & Lee, I. (2016). Classification of LIDAR data for generating a high-precision roadway map. *The International Archives of the Photogrammetry, Remote Sensing, and Spatial Information Sciences*, (XLI-B3), 251-254. doi:10.5194/isprs-archives-XLI-B3-251-2016
- Kreylos, O., Bawden, G. W., & Kellogg, L. H. (2008). Immersive visualization and analysis of LiDAR data. In *International Symposium on Visual Computing* (pp. 846-855). Springer, Berlin, Heidelberg. doi:10.1007/978-3-540-89639-5_81
- Manning, C. (2019, August). *Continental scale point cloud data management with Entwine*. Paper presented at FOSS4G, Bucharest, Romania.
- Pingel, T. J., Clarke, K. C., & McBride, W. A. (2013). An improved simple morphological filter for the terrain classification of airborne LIDAR data. *ISPRS Journal of Photogrammetry and Remote Sensing*, 77, 21-30. doi: 10.1016/j.isprsjprs.2012.12.002
- Scheutz, M. 2016. Potree: Rendering large point clouds in web browsers. Vienna University of Technology.
- Verma, U. & Butler, H. (2014). Potree [Computer software]. Retrieved from <https://github.com/verma/plasio>.
- Ware, M., Frank, E., Holmes, G., Hall, M., & Witten, I. H. (2001). Interactive machine learning: letting users build classifiers. *International Journal of Human-Computer Studies*, 55(3), 281-292.